

# **LIFE ENVIRONMENT STRYMON**

## **Ecosystem Based Water Resources Management to Minimize Environmental Impacts from Agriculture Using State of the Art Modeling Tools in Strymonas Basin**

**LIFE03 ENV/GR/000217**



### **Task 2. Monitoring Crop Pattern, Water quality and Hydrological Regime**

**Crop pattern identification in Strymonas basin using satellite image analysis  
Volume 4 (year 2007)**

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THE GOULANDRIS NATURAL HISTORY MUSEUM  
GREEK BIOTOPE / WETLAND CENTRE



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# **CHAPTER 1**

## **INTRODUCTION**

The aim of this work was to estimate the vegetation patterns and areas of the total study area for the year 2007. To achieve this task, like the three previous years, we used photo interpretation techniques for remote sensing data.

The Life Strymon project overall objective is to promote the sustainable management of surface waters and groundwater in Strymonas River Basin, assisting the implementation of the Water Frame Directive. (Chalkidis, et al. 2004. Water Quality and Hydrological Regime monitoring network.)

The identification and spatial distribution of crops in the Strymonas River Basin in early summer, is indispensable information for wise water usage during the months of July and August. During these months, we have the maximum demand for irrigation water. A detailed water distribution plan must be designed based on the crops water demand and the available water resources.

Remote sensing offers some relative fast and cost effective methods for crop identification using satellite image data. So it covers two major demands of the project: To have the spatial distribution of crops and to have them early in summer so that we can effectively design a water distribution plan.

Based on the experience gained in the previous 3 years of similar tasks, this year we took special care for two parameters which proved to be very important for successful crop pattern identification:

- Ordering an image set in the middle of spring
- Getting more signatures for wheat and Alfalfa

## **CHAPTER 2**

### **MATERIALS AND METHODS**

The method followed, can be described in the following general steps:

1. Data acquisition
2. Signature collection from the field
3. Data preparation
4. Data processing
5. Extraction of results

#### **2.1 Image acquisition**

For the purposes of the Life Strymon project, 14 multispectral satellite images that cover the whole study area were purchased from SPOT Imagery (Satellite Pour l'Observation de la Terre), under exact acquisition programming request. More precisely, 4 sets of images were purchased, each one including 2 scenes, one from the northeastern part and one from the southwestern part of the study area. SPOT imagery was selected because of the moderate spatial resolution (10m x 10m), reasonable price, data availability and spectral bands.

The image acquisition was programmed for the spring and summer of 2004, the summer of 2005 the summer of 2006 and for the spring and summer of 2007 in order to avoid cloud and ice coverage and to have the regarding crop pattern early in the summer, before the peaks of the irrigation period.. The programming request included detailed descriptions and technical requirements of the imagery needs, such as survey period, survey area and repeated acquisitions at specified time intervals for crop monitoring. The images were acquired by SPOT-4 and some by SPOT-5, depending on the time availability of the satellite's pass at the requested time period. Table 2.1.1 shows technical information and exact acquisition date and time of the satellite images.

**Table 2.1.1** Technical information and exact date and time of the acquisition of the eight SPOT images.

<b>Set</b>	<b>Scene</b>	<b>Satellite</b>	<b>Instrument</b>	<b>Resolution</b>	<b>Acquisition date</b>	<b>Acquisition time</b>
<b>1</b>	1	SPOT 4	HRVIR 2	10 m	23-April-2004	09:44:54
<b>1</b>	2	SPOT 4	HRVIR 1	10 m	29-April-2004	09:29:25
<b>2</b>	3	SPOT 4	HRVIR 1	10 m	25-May-2004	09:29:34
<b>2</b>	4	SPOT 4	HRVIR 2	10 m	14-June-2004	09:45:09
<b>3</b>	5	SPOT 5	HRG 2	10 m	14-July-2004	09:41:40
<b>3</b>	6	SPOT 5	HRG 2	10 m	25-August-2004	09:34:04
<b>4</b>	7	SPOT 5	HRG 2	10 m	22-June-2005	09:43:44
<b>4</b>	8	SPOT 4	HRVIR 2	10 m	9-July-2005	09:46:14
<b>5</b>	9	SPOT5	HRG 2	10 m	7-July-2006	09:34:14
<b>5</b>	10	SPOT5	HRG 2	10 m	17-June-2006	09:18:50
<b>6</b>	11	SPOT5	HRG 2	10 m	20-April-2007	09:13:36
<b>6</b>	12	SPOT5	HRG 2	10 m	29-April-2007	09:40:25
<b>7</b>	13	SPOT5	HRG 2	10 m	1-June-2007	9:36:53
<b>7</b>	14	SPOT5	HRG 2	10 m	11-June_2007	9:44:29

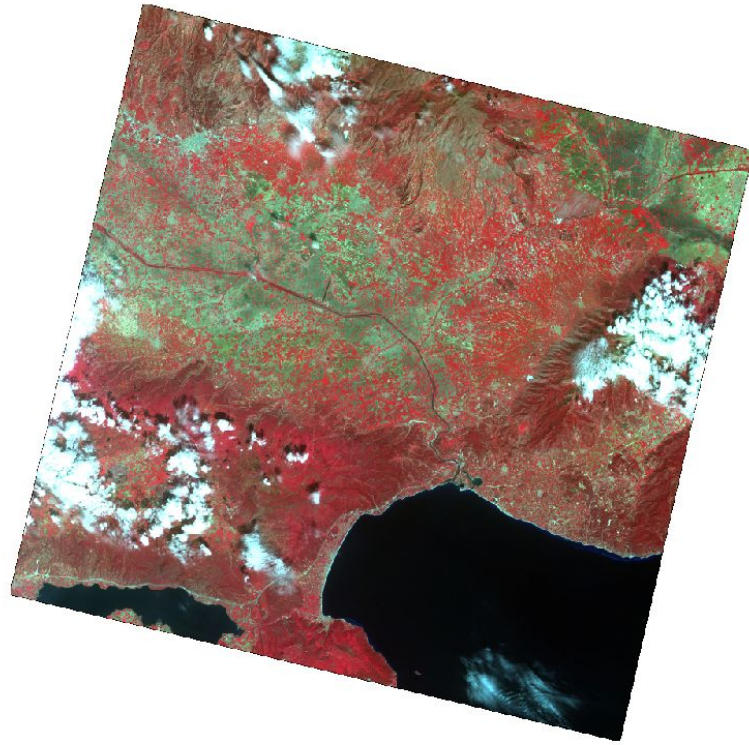
All images were preprocessed at Level 1A by SPOT Image France. Thus, a minimum radiometric correction was performed to them. This included the application of a linear model to compensate instrument effects and distortions, which are caused by differences in sensitivity of the elementary detectors of the viewing instrument.

## 2.2 Image preprocessing

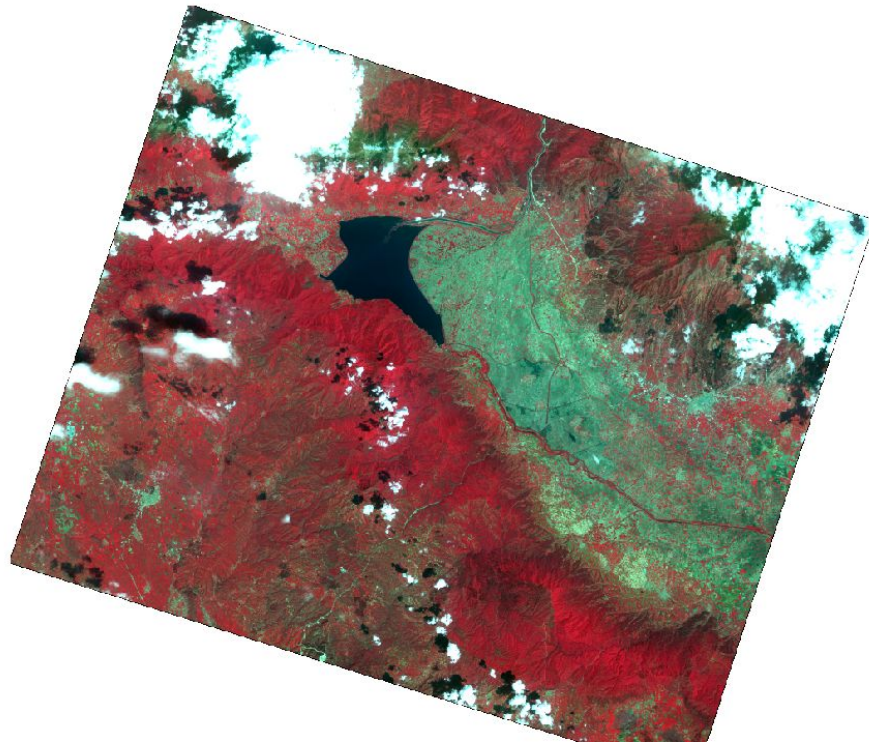
The four SPOT images from sets 6 and 7 that were used to identify the crop patterns of 2006 were firstly georeferenced to the Greek Geodetic Reference System EGSA '87<sup>1</sup> using ERDAS IMAGINE version 8.4. "Image to map" and "image to

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<sup>1</sup> The Greek Geodetic Reference System (EGSA '87) is a Transverse Mercator projection that uses the spheroid of GRS80 and a scaling factor of 0.9996. It is the main reference system that is used in Greece

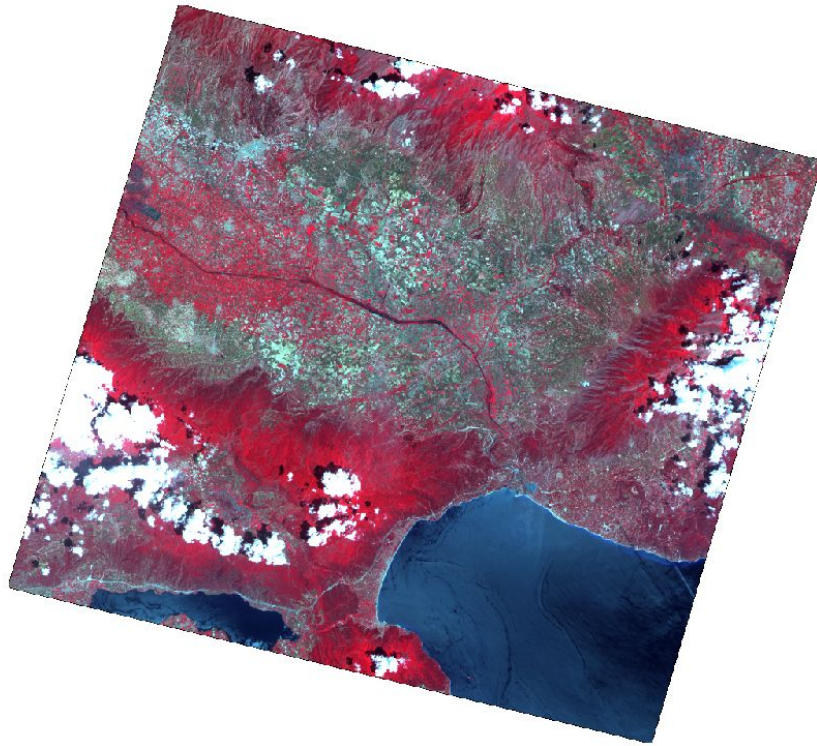


**Figure 2.2.1** Scene 11 (April 20, 2007) from the SE part, georeferenced to EGSA '87.

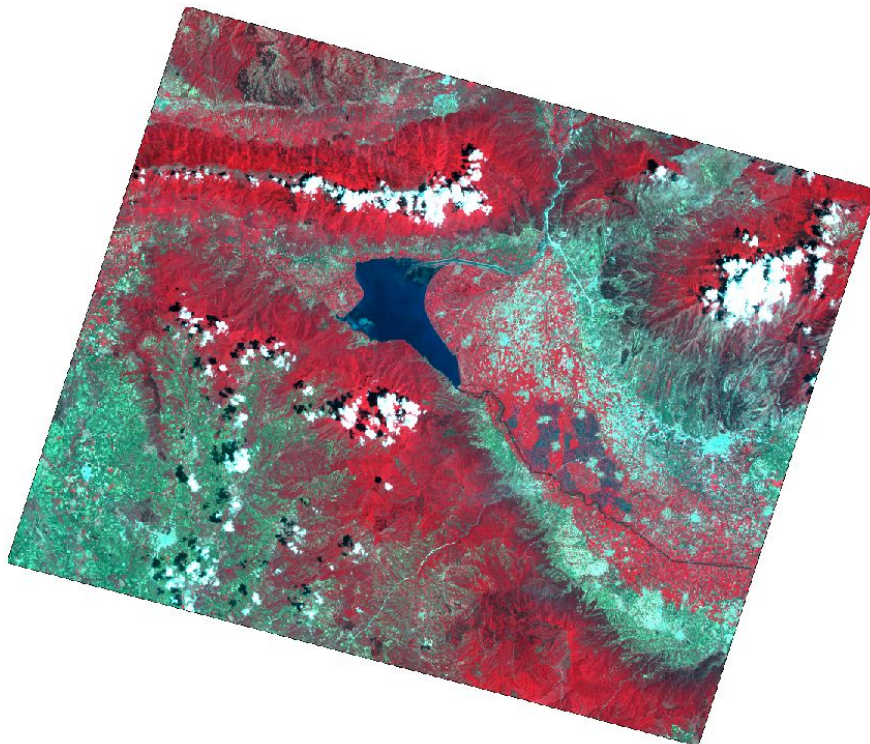


**Figure 2.2.2** Scene 12 (April 29, 2007) from the NW part, georeferenced to EGSA '87.





**Figure 2.2.3** Scene 13 (June 1, 2007) from the SE part, georeferenced to EGSA '87.



**Figure 2.2.4** Scene 14 (June 11, 2007) from the NW part, georeferenced to EGSA '87.

image” coordinate transformations were applied for the georeference, using well defined ground control points from topographic maps (scale 1: 50.000). The first order polynomial method was preferred for the transformations, because of the suitability of this method when dealing with relatively flat areas, such as is the case of the Strymonas River basin. The bilinear interpolation was selected for resampling the images, because of its higher spatial accuracy. Figures 2.2.1 to 2.2.4 show the images which resulted from that procedure.

### **2.3 Additional materials used**

In addition to the satellite images, which were the primary source of spatial data, the following hardware used to accomplish the task:

- Computer system with Pentium/2.8 CPU, 1,5GB RAM, 300GB total disk space and windows XP operating system
- ArcGis 9.0 GIS software (both desktop and workstation)
- ArcPad V.6.0.1
- Erdas Imagine V. 8.4
- ArcView 3.2 with Image Analysis extention
- Microsoft office 2003 pro, office application.
- Trimble RECON handheld computer
- Pertec GPS system.
- 4MP digital camera (Olympus 770)
- Tape recorder

### **2.4 Signature collection**

Field visits during the summer of 2007 were performed for vegetation signature collection.

Based on the experience gained in the previous years of application, a detailed route was designed on the map before each trip for signature collection. A general and detailed map of this route for the 27/6/07 route is given to fig. 2.4.1 and 2.4.2.

A total of **208** signatures were collected from **10** different crop samples. The position of all these signatures was recorded using the GPS and ArcPad system.

A complete tracklog file from the GPS was also collected with a 10 sec time step. In this file the time and position of the GPS was recorded every 10 seconds and when the accuracy of the GPS was less than 12 m.

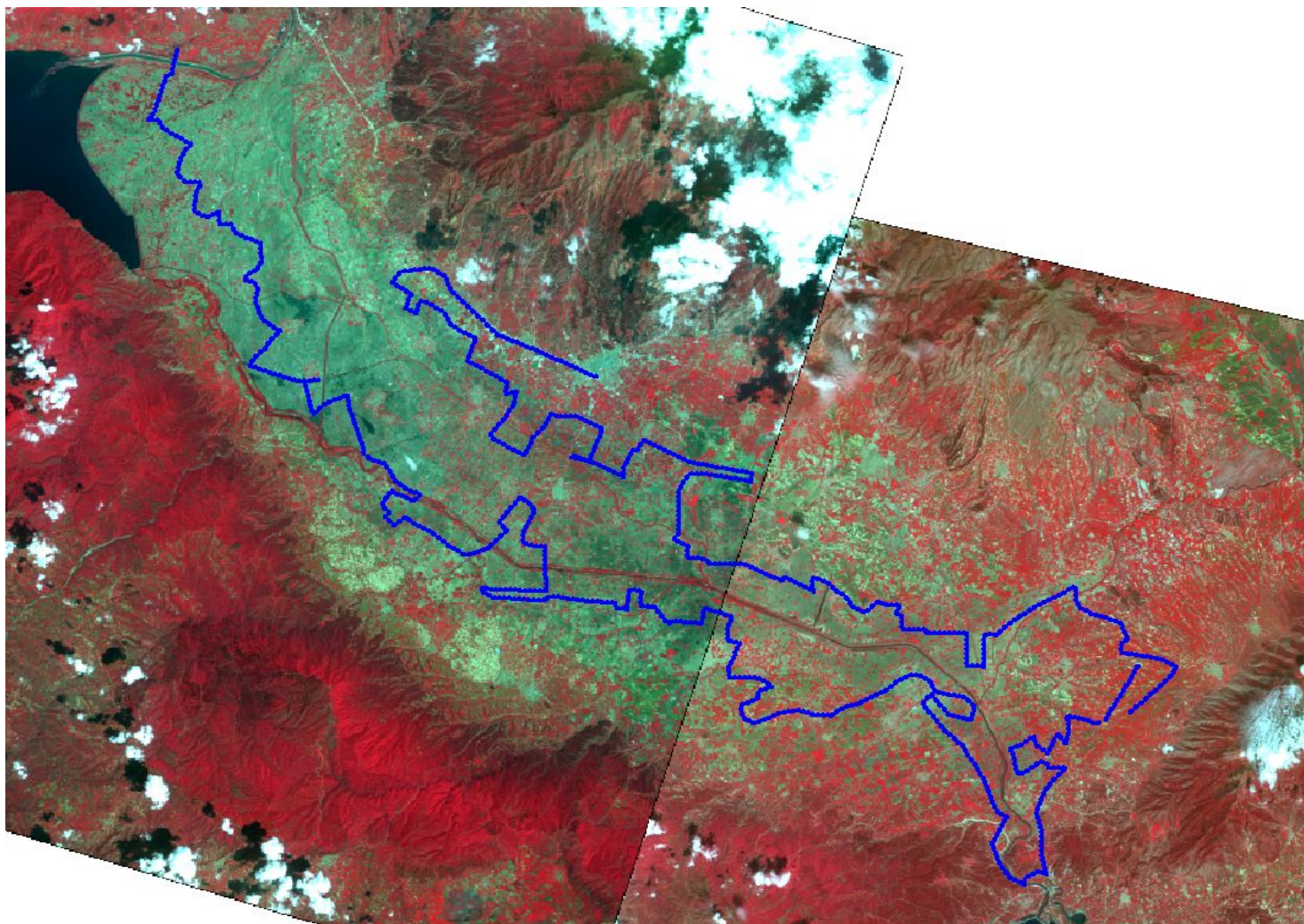
Additionally, detailed descriptions of the signatures were recorded.

More than 40 photographs were taken during each visit from the vegetation signatures.

**Table 2.4.1** Samples per crop collected from the two field visits.

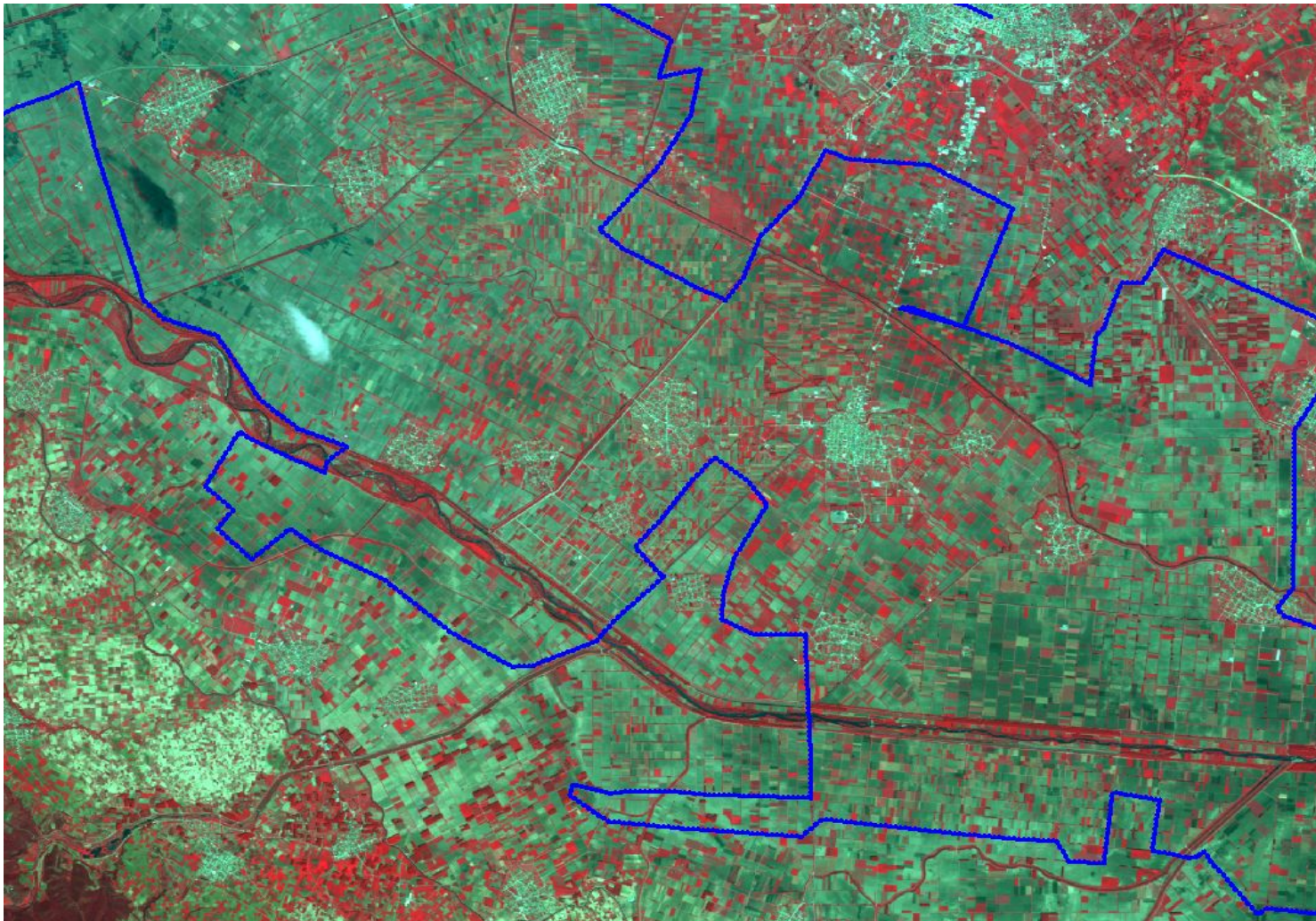
<b>Corp</b>	<b>Number of samples</b>
Maize	34
Tobacco	7
Cotton	38
Alfalfa	32
Rice	18
Poplar plantation	18
Sugar beets	19
Wheat	21
Olive groves	15
Almond groves	6





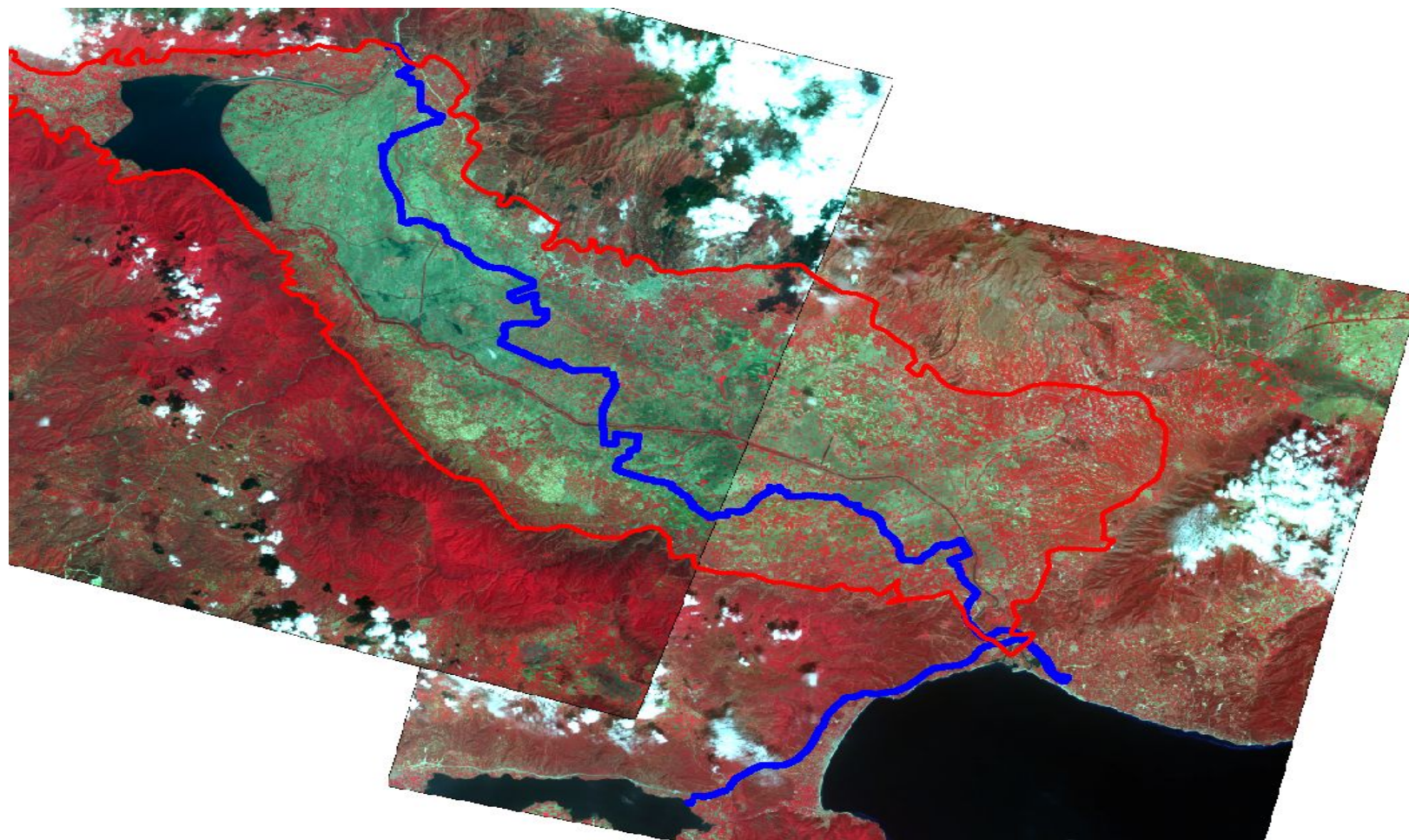
**Figure 2.4.1** The planning of the route (blue line) to be followed for signature collection





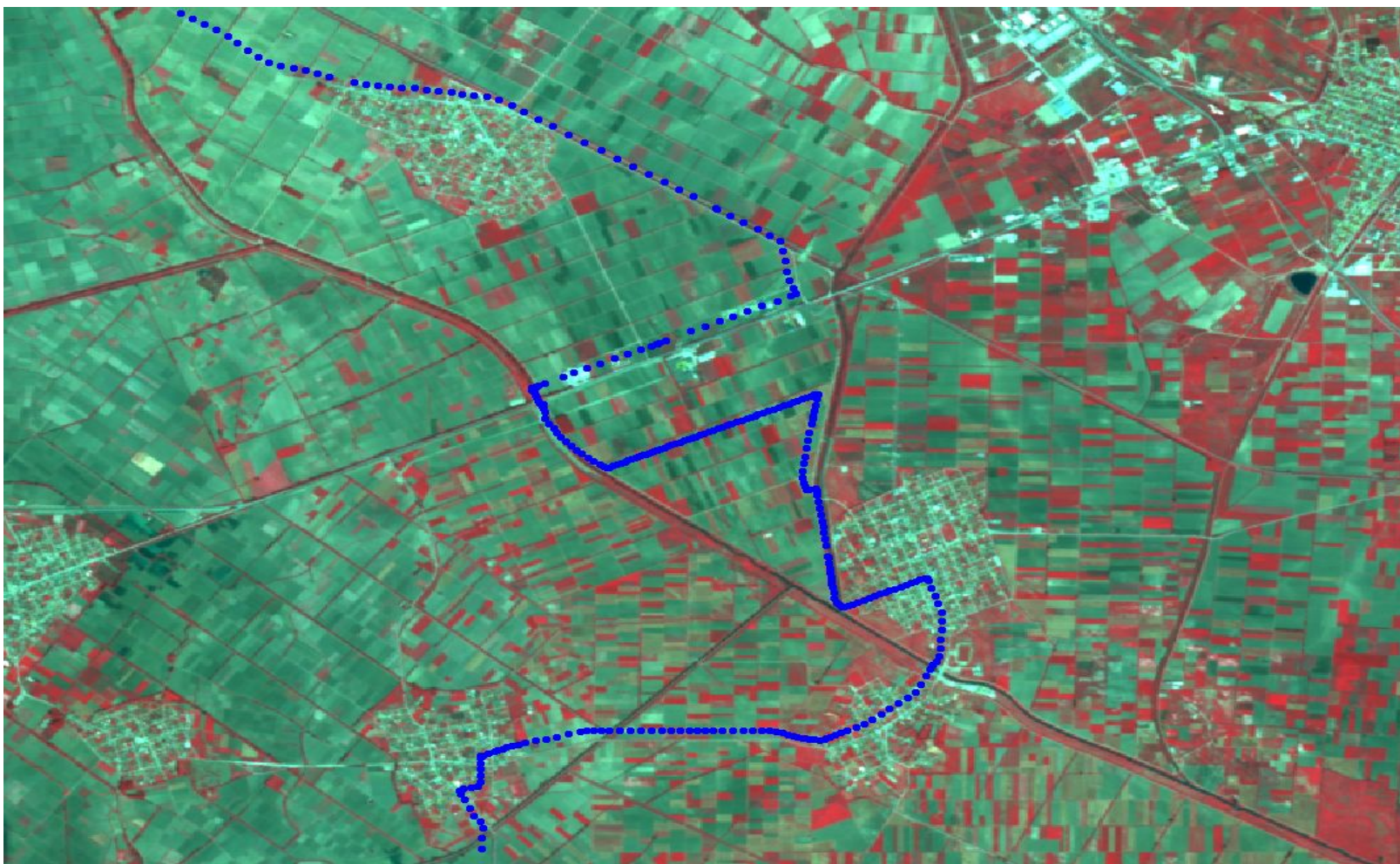
**Figure 2.4.2** The planning of the route (blue line) to be followed for signature collection (detail)





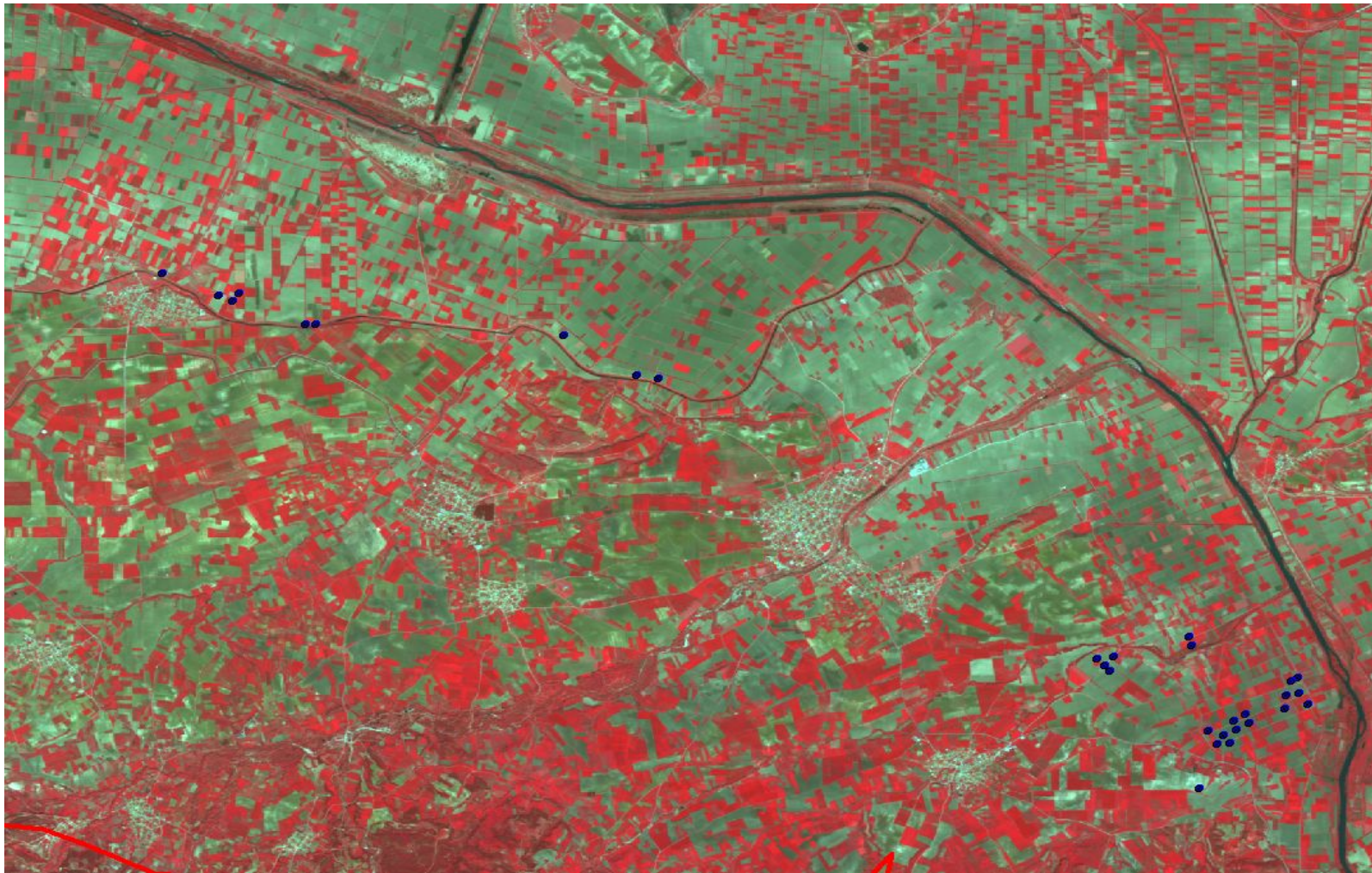
**Figure 2.4.3** A sample route from a field visit in June 2007. The red line is the study area boundaries and the blue dots are the GPS's tracklog points.





**Figure 2.4.4** Detail from Figure 2.4.3 showing the points of tracklog collected.





**Figure 2.4.5** Signatures collected from a field visit (blue dots).





**Fig 2.4.6** Cotton and maize field



**Fig 2.4.7** Blossomed alfalfa field





**Fig 2.4.8** Sugar beets.



**Fig 2.4.9** Alfalfa field ready for harvest.





**Fig 2.4.10** Cotton field near Poplar plantation





**Fig 2.4.11** Maize field



**Fig 2.4.12** Olive trees near a harvested wheat fields.



**Fig 2.4.13** Rice field.

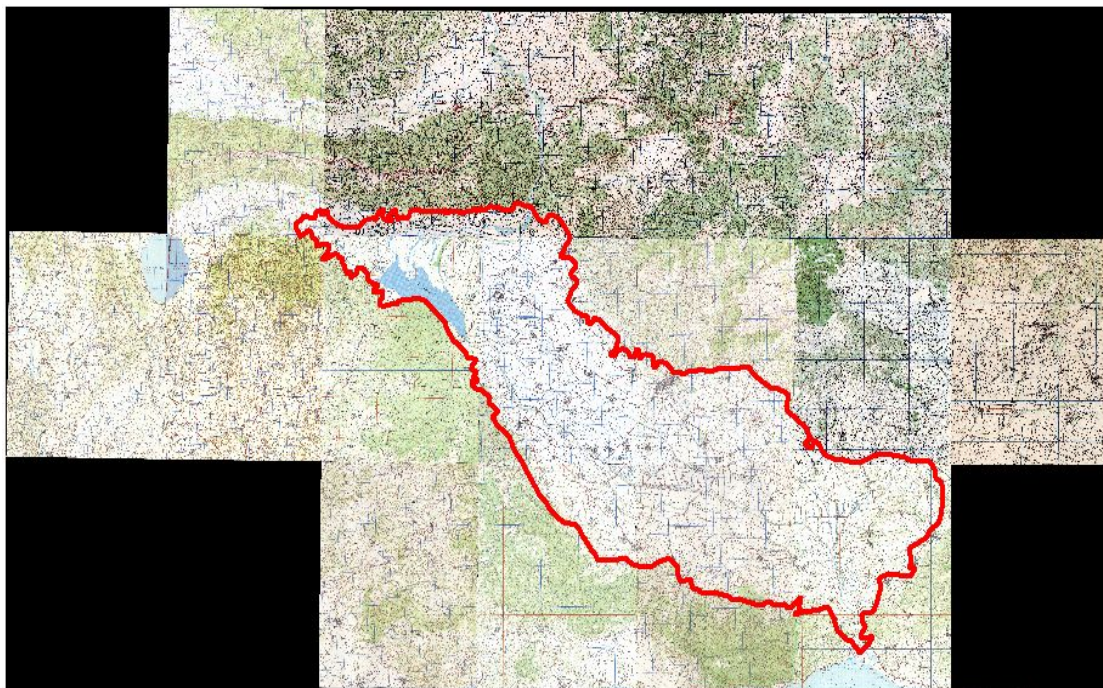
## **2.5 Auxiliary data collection and preparation**

Satellite images and signatures are not enough for a successful image classification. There is always a need for some auxiliary data which can be used as a general background or for some specialized tasks during the data preparation or the classification procedures. A detailed description of the auxiliary data used in this project is shown in table 2.5.1.

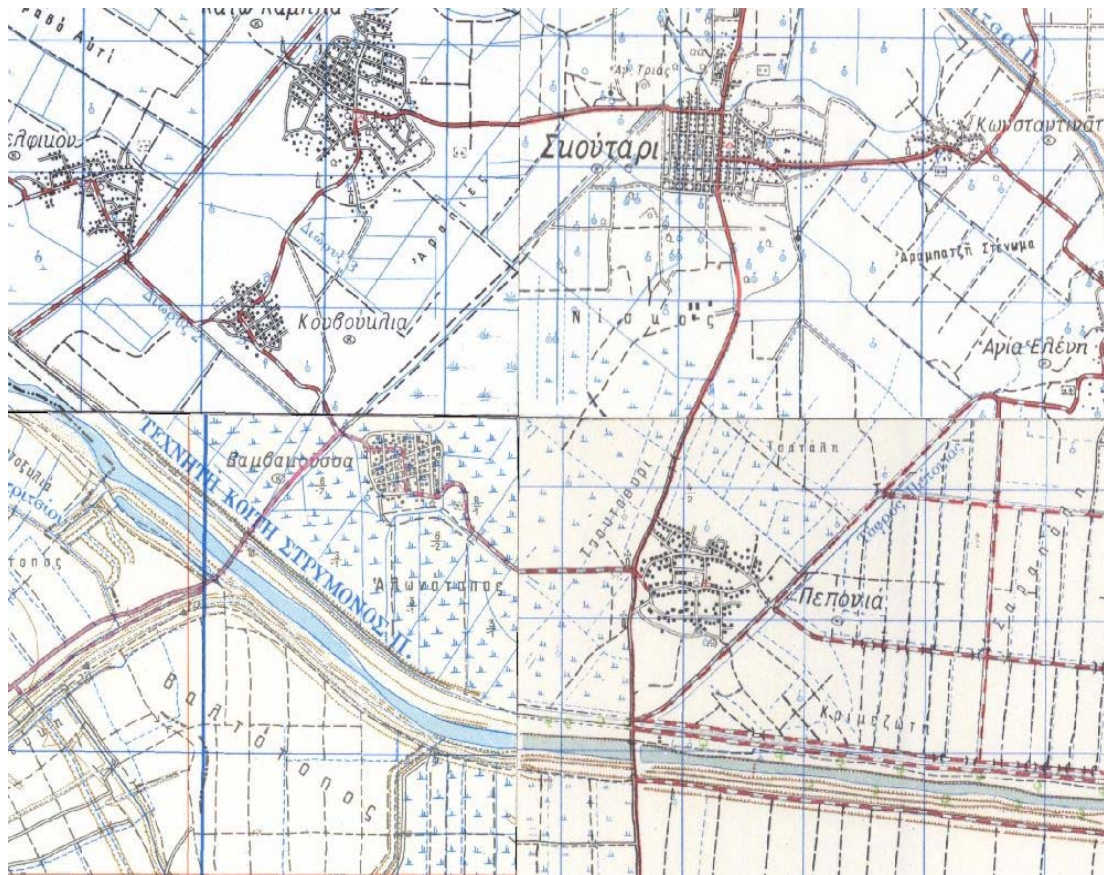


**Table 2.5.1** Auxiliary data collection

<b>Data</b>	<b>Source</b>	<b>Preparation</b>	<b>Used for..</b>
Topographic maps in 1:50.000 scale	Hellenic Army Geographic Survey	Scanning of 16 maps at 300dpi. Georeference. Composition of a unified background of the study area	General background, field map, digitization of auxiliary data (villages, streams etc.)
Digital Elevation Model (DEM)	EKBY	Interpolation of hypsography and hydrology data	Rectification, general background
Corine Landcover	EKBY archive	-	Additional background information



**Fig 2.5.1** 16 topographic maps were scanned, georeferenced and combined to compose a unique topographic background of the study area (red line)



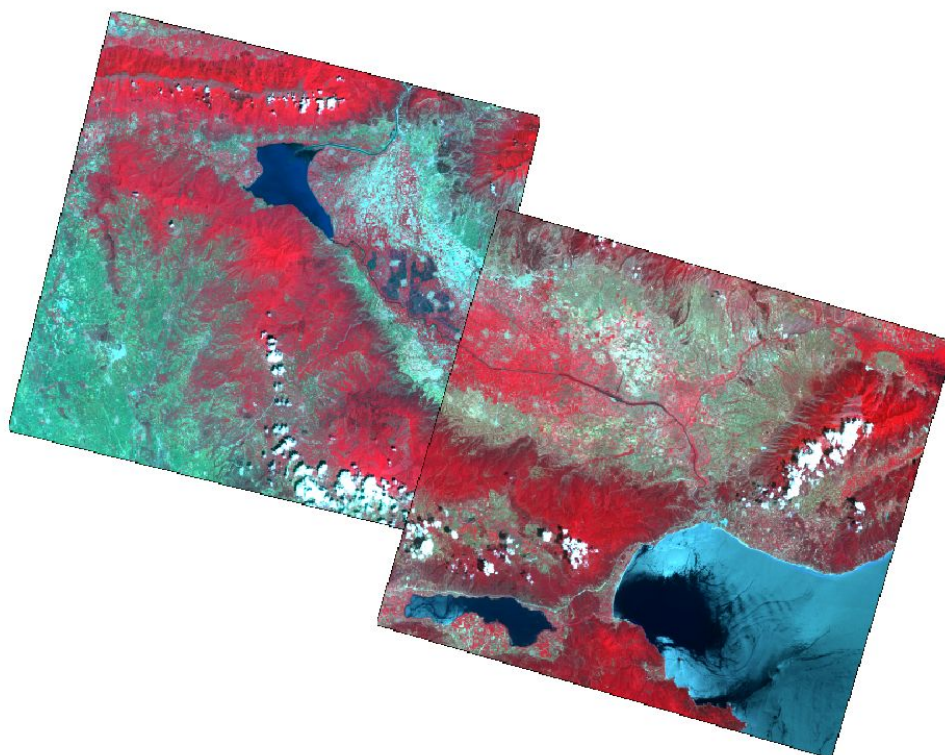
**Fig 2.5.2** Detail of the topographic background (junction of 4 maps)

## **2.6 The classification procedure**

### **2.6.1 Preparation of satellite images**

Using the topographic background the two satellite images were georeferenced in EGSA87 projection system.





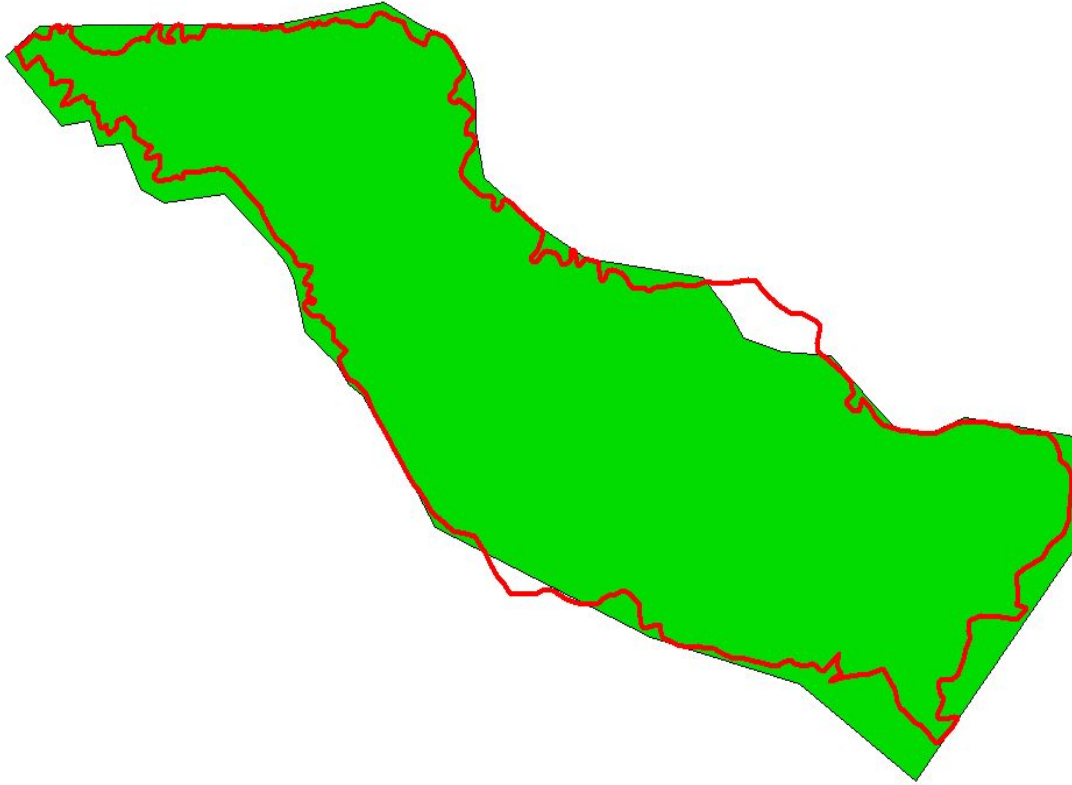
**Figure 2.6.1** Sixth set of SPOT images georeferenced in EGSA87 projection system.

### **2.6.2 More detailed boundaries of the study area**

As mentioned in the 2006 report and after a close examination of the original boundaries of the study area, we found that in many cases some forested and mountainous areas were included. As these areas were out of the interest of this study and additionally could have a negative effect in the classification procedure, we decided to re-digitize the boundary polygon in more detail to exclude these areas. The new boundaries also included some agricultural areas not included in the original boundaries

The area of the new polygon is **173,727 ha** while the old boundaries covered an area of 192,689 ha.

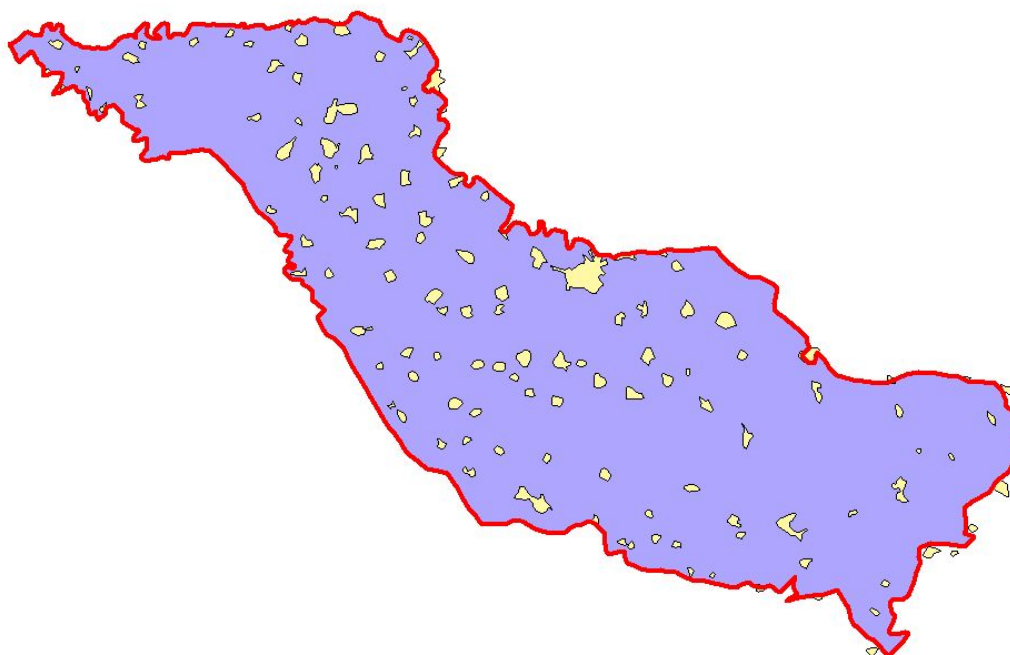




**Figure 2.6.2** The original study area (green polygon) and the area after the detailed digitization (red line).

### **2.6.3 Extraction of inhabited areas**

In this step we took out from our study area all the cities and villages. The boundaries of these areas were delivered from the CORINE landcover layer and corrected using the satellite images. These areas are easily recognized in the satellite images so the correction of the CORINE layer was a rather easy procedure.



**Figure 2.6.3** Inhabited areas (yellow polygons) which were taken out of the study area.

#### **2.6.4 Water body and clouds extraction**

The study area contains some rather large water bodies like Kerkini lake, Strymon and Agitis rivers and Belitsa stream. These bodies cover a significance percentage of our study area and could have some negative effects in the accuracy of the classification.

In the same category fall the areas covered by clouds and their shadows. Fortunately cloud – covered areas are only on the south-east of the study area and cover less than 2% of the total area.

So our next step was to take out from the satellite images all the areas covered by water bodies, clouds and cloud – shadows.

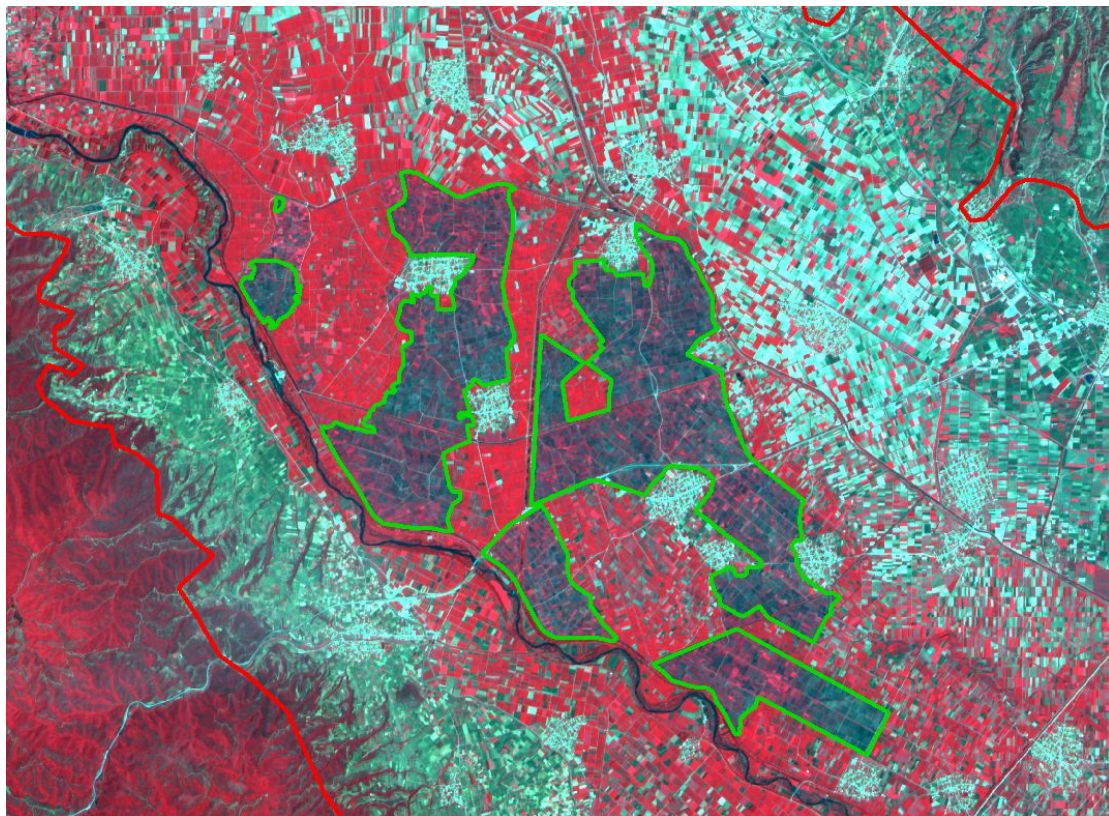
The water bodies were easily delineated using unsupervised classification. After few test – classifications we easily found the pixels of water bodies in the satellite images and we took them out. With a similar procedure we also found the areas covered by clouds and their shadows and deleted them from the satellite images.

### 2.6.5 Rice beds extraction

As the satellite images were taken in the end of June and in the beginning of July, the rice fields of the area were full of water. These areas were easily delineated after some test unsupervised classifications.

A total area of **4185.65 ha** was as rice fields.

After the delineation these areas were taken out from the images. Thus we continued the classification with fewer classes and less pixels to process.



**Figure 2.6.5** Delineation of rice beds (green line)

### 2.7 Supervised classification

After extracting all the above areas (mountainous, inhabited, water bodies, clouds, cloud shadows, rice fields) the remaining pixels were classified using supervised classification based on the signatures that we collected.

The classification process was repeated several times using different signatures. An accuracy assessment was performed after each classification to estimate the effectiveness of the procedure. We also performed some fine – tuning and corrections

in the position of the signatures based on the results of the classification and accuracy assessment.

As the study area contains a lot of non – agricultural land uses (roads, streams, ditches, factories etc.), it was necessary to follow a step by step classification (one step for every class) so that the remaining area to correspond to the no – agricultural uses. This method could be described in the following steps:

1. Based on the available signatures and some draft-classification tests we choose the class we are going to extract
2. Perform the supervised classification based on the class's signatures
3. Perform accuracy assessment
4. Make corrections and fine tuning of the signatures and their position
5. Repeat from step 2 until we get the best accuracy assessment
6. Save the layer representing the class in raster format, convert to vector and estimate the area of the class
7. Remove from the satellite image the pixels corresponding to the class we estimated
8. Repeat previous steps 1 – 7 in the remaining image's pixels and for the rest of the classes.
9. After the completion of the above procedure the remaining pixels, represent no agricultural uses.

The results and conclusion of the application of the above procedure are presented in the next chapter.

## **CHAPTER 3**

### **RESULTS AND DISCUSSION**

#### **3.1 Results**

The results of the classification are presented in table 3.1.1

**Table 3.1.1** Total area and accuracy assessment for each cultivation as occurred from the classification procedure.

	<b>Cultivation</b>	<b>Area (ha)</b>	<b>Classification Accuracy assessment (%)</b>
1	Maize	38673	95
2	Tobacco	3865	71
3	Cotton	42763	71
4	Alfalfa	9764	80
5	Rice	4228	100
6	Poplar plantation	6874	96
7	Sugar beets	978	78
9	Olive groves	3114	68
10	Almond groves	9432	66









### **3.2 Discussion**

Based on the above description of the classification procedure and the experience gained in testing the signatures and estimating the accuracy of the results on the last four years, we can come to some conclusions. There are also some issues raised during this procedure, affecting the project's targets and some suggestions.

All the above are discussed below:

#### **3.2.1 Mosaicing**

A major fallback and time consuming issue was the fact that it was not possible to mosaic the two images in one. Even that in this year the time gaps between the two images was 9 days (for the April set) and 10 days (for the June set) mosaicking these images was not possible. The two images had quite different pixel values for the same classes and practically it was impossible to archive a good mosaic of the two images.

It's worth mentioning that all the four images were taken around 09:15 to 09:45 in the morning. So the time of the day was not a restricting factor to mosaic the images. The real restricting factor was the ~10days time gap.

This resulted in performing two separate classification for each image for every class. This was a rather time consuming procedure which also increased the risk level for errors.

A solution for this problem is to order the images with a maximum time gap of 3 days. This is not always possible and can be affected by the available programmable options of the satellite, the cloud coverage, and the satellite image provider. (Leica Geosystems, 2002. Erdas Spectral Analysis)

#### **3.2.2 Signature collection**

This year's signature collection was performed using the same equipment with year's 2005 and 2006. This combination of hardware, software and technique proved very effective and productive for signature collection.

This combination, basically consisted by the GPS's track log file with the oral descriptions recorded in a tape recorder during the field visits, was also very useful in

the signature evaluation procedure and in the completion of more signatures on the screen.

Additionally, this year, before every trip for signature collection, a detailed rout was planed using topographic maps

### **3.2.3 Separetability of classes**

Some separetability problems were encountered in specific classes. i.e. between tobacco, cotton and sugar beets. This was a rather difficult problem and we have to use some advanced techniques to face it. It was also necessary to perform some preprocessing to achive better results.

The accuracy assessment achieved for the above classes has better values than in 2005 and 2006 because we now used both sets of satellite images and change detection techniques.

### **3.2.4 Classes used and classification area**

As mentioned in the 2005 and 2006 report, there are some questions which were raised during the classification process and we need to be addressed as they affect directly the achievement of the project's targets:

- Do we need to know the spatial distribution of all these classes in our study area to achieve the project's targets?
- Do we need all these classes or less?
- Which of these classes are more important?
- Can we separate the study area in some zones where we need high values of classification accuracy assessment?

A good approach to answer the first three questions is to have a draft estimation of the main water consuming classes for each cultivation period. As some of them are standard for each year (rice, maize, cotton, sugar beets) the decision has to be taken for some of them (tomatoes, potatoes, etc.). A similar decision has to be taken for parcels covered by trees: Do we really need the areas covered by walnut trees?

The last of the above questions affects the available irrigation networks. It is obvious that we need high values of accuracy assessment in areas covered by the existing

irrigation networks as the consumption and need for water there is very important for an effective water management.

In this year we decided to omit some crops from the classification process to achieve better accuracy assessment for the rest most important classes. On the other hand the omitted classes had little coverage of the total area and the consumption of the irrigation water by them is limited.

### **3.2.5 Alfalfa, wheat, and poplar plantations**

As mentioned in the previous reports, alfalfa is a very special case of crop because it does not have the same (or similar) pixel values in the same area, the same time. This happens because some fields may have just been harvested (so they look like bare land), some may have little growth (because of a previous harvest) or some may have a complete growth.

There is also a separability problem between harvested wheat fields and uncultivated areas and just-harvested alfalfa. This happens because these three classes look the same.

In previous reports suggested that a good (and possibly the only) practical solution to this problem is to use two or more layers of satellite images, to detect the changes and combine these layers for the classification process. So we have one more good reason (in addition to the one we described in 3.2.3) to obtain and use two sets of images for the classification process. (Leica Geosystems, 2002. Erdas Imagine Tour Guide, Leica Geosystems, 2002. Erdas Imagine Field Guide).

So in this year we managed to get a second set of satellite images in the middle of April and used this additional source of data to successfully find the areas covered with alfalfa and wheat. During the April, wheat fields have a well – distinguished green color and with alfalfa and poplar plantations they are the only fields during this period with strong absorption in the area of green. So it is much more easier and errorless to classify these three classes with the April image than to classify them with all the other classes.

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